How to generate single-tap and double-tap interrupts using BMI160 accelerometer

Bosch Sensortec





Page 2 Confidential

Table of contents

1	INT	RODUCTION	3
2	SAI	MPLE CODE	4
3	TES	ST RESULTS	5
4	LEC	GAL DISCLAIMER	6
	4.1	ENGINEERING SAMPLES	6
	4.2	PRODUCT USE	6
	4.3	APPLICATION EXAMPLES AND HINTS	6
5	DO	CUMENT HISTORY AND MODIFICATION	7



Page 3
Confidential

1 Introduction

BMI160 IMU combo chip includes 16-bit 3-axis digital accelerometer (ACC) and 16-bit 3-axis gyroscope (GYR). Single-tap and double-tap interrupts are a built-in feature inside BMI160 accelerometer. It can be used to wake up a system in low power mode in order to save overall power consumption of the system. The working principle of single-tap and double-tap is described in BMI160 datasheet online at https://ae-

<u>bst.resource.bosch.com/media/_tech/media/datasheets/BST-BMI160-DS000-07.pdf</u> on page 28 Section 2.3.4.

After BMI160 is powered on, both accelerometer and gyroscope will be in suspend mode. Users need to write value of 0x12 to command register 0x7E to bring the accelerometer to low power mode (LPM) with default +/-2g full scale (FS) range and 100Hz output data rate (ODR). Then users can write value of 0x88 to register 0x40 for no average. At this time BMI160 accelerometer consumes about 45uA compared to normal mode of 180uA.

The single-tap interrupt will be generated when two of the following conditions are valid:

- The slope or differential acceleration exceeds the int_tap_th (tap threshold). Within the int_tap_shock amount of time, all other slope accelerations will be ignored
- After the tap_shock amount of time, within the int_tap_quiet amount of time there are also no slope or differential acceleration exceeds the int_tap_th

The single-tap interrupt will be cleared automatically when the above conditions are no longer valid.

The double-tap interrupt will be generated when three of the following conditions are valid:

- The slope or differential acceleration exceeds the int_tap_th (tap threshold). Within the
 int_tap_shock amount of time, all other slope accelerations will be ignored
- After the tap_shock amount of time, within the int_tap_quiet amount of time there are also no slope or differential acceleration exceeds the tap_th
- Within int tap dur amount of time the second of single-tap event happened

The double-tap interrupt will be cleared automatically when the above conditions are no longer valid.



Page 4
Confidential

2 Sample code

Below is the pseudo code to initialize the BMI160 accelerometer for single-tap interrupt on INT1 pin and double-tap on INT2 pin. The settings can be fine-tuned to meet the requirements in different applications.

```
void init BMI160 ACC(void)
{
       // basic configurations
       Write value of 0xB6 to register 0x7E;
                                                   // soft reset BMI160 to default settings. Both
                                                   accelerometer and gyroscope are in suspend
                                                   mode
       Delay 55ms;
                                                   // for BMI160 to stabilize
       Write value of 0x12 to register 0x7E;
                                                   // set the accelerometer to LPM mode
                                                   // for BMI160 accelerometer to stabilize
       Delay 5ms;
       Write value of 0x88 to register 0x40;
                                                   // set ODR to 100Hz with no average (45uA)
       // interrupt configuration
       Write value of 0xAA to register 0x53;
                                                   // set both INT1 pin and INT2 pin as output,
                                                    active-high, push-pull
       Write value of 0x09 to register 0x54;
                                                   // temporarily latch the interrupt for 80ms
       Write value of 0x20 to register 0x55;
                                                   // route single-tap interrupt to INT1 pin
       Write value of 0x10 to register 0x57;
                                                   // route double-tap interrupt to INT2 pin
       // tap sensing configuration
       Write 0x04 to register 0x63;
                                                   // default value for 50ms int tap shock,
                                                    30ms int tap quiet and 250ms int tap dur.
                                                    (These durations can be fine-tuned)
       Write 0x0A to register 0x64;
                                                   // default value for 625mg int tap th (can be
                                                   fine-tuned)
       // enable single-tap and double-tap interrupt
       Write 0x30 to register 0x50;
                                                   // enable single-tap and double-tap interrupt
}
```

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Page 5 Confidential

3 Test results

Below is the screenshot of the Development Desktop software. The software works with the APP2.0 application base board that has the BMI160 shuttle board plugged in.

Figure 1 shows that the single-tap interrupts on INT1 pin and double-tap interrupts on INT2 pin are generated. The tap motion can come from any directions.

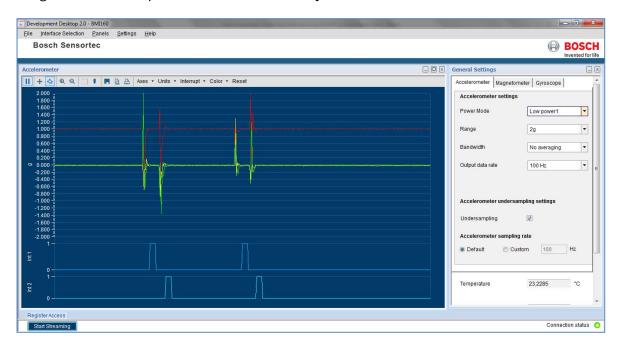


Figure 1: Single-tap and double-tap interrupts

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Page 6
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4 Legal disclaimer

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Page 7
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5 Document history and modification

Rev. No	Chapter	Description of modification/changes	Date
1.0		Document creation	August 22 nd , 2017

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